

Kristen Grauman - Bastian Leibe

Visual Object Recognition



Visual Object Recognition Bastian Leibe

Damian Ryan Eads

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Visual Object Recognition Kristen Grauman, Bastian Leibe, 2022-05-31 The visual recognition problem is central to computer vision research From robotics to information retrieval many desired applications demand the ability to identify and localize categories places and objects This tutorial overviews computer vision algorithms for visual object recognition and image classification We introduce primary representations and learning approaches with an emphasis on recent advances in the field The target audience consists of researchers or students working in AI robotics or vision who would like to understand what methods and representations are available for these problems. This lecture summarizes what is and isn t possible to do reliably today and overviews key concepts that could be employed in systems requiring visual categorization Table of Contents Introduction Overview Recognition of Specific Objects Local Features Detection and Description Matching Local Features Geometric Verification of Matched Features Example Systems Specific Object Recognition Overview Recognition of Generic Object Categories Representations for Object Categories Generic Object Detection Finding and Scoring Candidates Learning Generic Object Category Models Example Systems Generic Object Recognition Other Considerations and Current Challenges Conclusions A Concise Introduction to Models and Methods for Automated Planning Hector Geffner, Blai Bonet, 2022-05-31 Planning is the model based approach to autonomous behavior where the agent behavior is derived automatically from a model of the actions sensors and goals The main challenges in planning are computational as all models whether featuring uncertainty and feedback or not are intractable in the worst case when represented in compact form In this book we look at a variety of models used in AI planning and at the methods that have been developed for solving them The goal is to provide a modern and coherent view of planning that is precise concise and mostly self contained without being shallow For this we make no attempt at covering the whole variety of planning approaches ideas and applications and focus on the essentials The target audience of the book are students and researchers interested in autonomous behavior and planning from an AI engineering or cognitive science perspective Table of Contents Preface Planning and Autonomous Behavior Classical Planning Full Information and Deterministic Actions Classical Planning Variations and Extensions Beyond Classical Planning Transformations Planning with Sensing Logical Models MDP Planning Stochastic Actions and Full Feedback POMDP Planning Stochastic Actions and Partial Feedback Discussion Bibliography Robot Learning from Human Teachers Sonia Chernova, Andrea L. Thomaz, 2022-06-01 Learning from Author's Biography Demonstration LfD explores techniques for learning a task policy from examples provided by a human teacher The field of LfD has grown into an extensive body of literature over the past 30 years with a wide variety of approaches for encoding human demonstrations and modeling skills and tasks Additionally we have recently seen a focus on gathering data from non expert human teachers i e domain experts but not robotics experts In this book we provide an introduction to the field with a focus on the unique technical challenges associated with designing robots that learn from naive human teachers We begin in

the introduction with a unification of the various terminology seen in the literature as well as an outline of the design choices one has in designing an LfD system Chapter 2 gives a brief survey of the psychology literature that provides insights from human social learning that are relevant to designing robotic social learners Chapter 3 walks through an LfD interaction surveying the design choices one makes and state of the art approaches in prior work First is the choice of input how the human teacher interacts with the robot to provide demonstrations Next is the choice of modeling technique Currently there is a dichotomy in the field between approaches that model low level motor skills and those that model high level tasks composed of primitive actions We devote a chapter to each of these Chapter 7 is devoted to interactive and active learning approaches that allow the robot to refine an existing task model And finally Chapter 8 provides best practices for evaluation of LfD systems with a focus on how to approach experiments with human subjects in this domain **Advancement of Deep** Learning and its Applications in Object Detection and Recognition Roohie Naaz Mir, Vipul Kumar Sharma, Ranjeet Kumar Rout, Saived Umer, 2023-05-10 Object detection is a basic visual identification problem in computer vision that has been explored extensively over the years Visual object detection seeks to discover objects of specific target classes in a given image with pinpoint accuracy and apply a class label to each object instance Object recognition strategies based on deep learning have been intensively investigated in recent years as a result of the remarkable success of deep learning based image categorization In this book we go through in detail detector architectures feature learning proposal generation sampling strategies and other issues that affect detection performance The book describes every newly proposed novel solution but skips through the fundamentals so that readers can see the field's cutting edge more rapidly Moreover unlike prior object detection publications this project analyses deep learning based object identification methods systematically and exhaustively and also gives the most recent detection solutions and a collection of noteworthy research trends The book focuses primarily on step by step discussion an extensive literature review detailed analysis and discussion and rigorous experimentation results Furthermore a practical approach is displayed and encouraged Metric Learning Aurélien Muise, Amaury Yang, 2022-05-31 Similarity between objects plays an important role in both human cognitive processes and artificial systems for recognition and categorization How to appropriately measure such similarities for a given task is crucial to the performance of many machine learning pattern recognition and data mining methods. This book is devoted to metric learning a set of techniques to automatically learn similarity and distance functions from data that has attracted a lot of interest in machine learning and related fields in the past ten years In this book we provide a thorough review of the metric learning literature that covers algorithms theory and applications for both numerical and structured data We first introduce relevant definitions and classic metric functions as well as examples of their use in machine learning and data mining We then review a wide range of metric learning algorithms starting with the simple setting of linear distance and similarity learning We show how one may scale up these methods to very large amounts of training data To go beyond the linear case

we discuss methods that learn nonlinear metrics or multiple linear metrics throughout the feature space and review methods for more complex settings such as multi task and semi supervised learning Although most of the existing work has focused on numerical data we cover the literature on metric learning for structured data like strings trees graphs and time series In the more technical part of the book we present some recent statistical frameworks for analyzing the generalization performance in metric learning and derive results for some of the algorithms presented earlier Finally we illustrate the relevance of metric learning in real world problems through a series of successful applications to computer vision bioinformatics and information retrieval Table of Contents Introduction Metrics Properties of Metric Learning Algorithms Linear Metric Learning Nonlinear and Local Metric Learning Metric Learning for Special Settings Metric Learning for Structured Data Generalization Guarantees for Metric Learning Applications Conclusion Bibliography Authors Biographies Decision-Making from Rank Data Lirong Xia, 2019-02-06 The ubiquitous challenge of learning and decision making from rank data arises in situations where intelligent systems collect preference and behavior data from humans learn from the data and then use the data to help humans make efficient effective and timely decisions Often such data are represented by rankings This book surveys some recent progress toward addressing the challenge from the considerations of statistics computation and socio economics We will cover classical statistical models for rank data including random utility models distance based models and mixture models We will discuss and compare classical and state of the art algorithms such as algorithms based on Minorize Majorization MM Expectation Maximization EM Generalized Method of Moments GMM rank breaking and tensor decomposition We will also introduce principled Bayesian preference elicitation frameworks for collecting rank data Finally we will examine socio economic aspects of statistically desirable decision making mechanisms such as Bayesian estimators This book can be useful in three ways 1 for theoreticians in statistics and machine learning to better understand the considerations and caveats of learning from rank data compared to learning from other types of data especially cardinal data 2 for practitioners to apply algorithms covered by the book for sampling learning and aggregation and 3 as a textbook for graduate students or advanced undergraduate students to learn about the field This book requires that the reader has basic knowledge in probability statistics and algorithms Knowledge in social choice would also help but is not required Pattern **Recognition** Katrin Franke, Klaus-Robert Müller, Bertram Nickolay, Ralf Schäfer, 2006-09-11 This book constitutes the refereed proceedings of the 28th Symposium of the German Association for Pattern Recognition DAGM 2006 The book presents 32 revised full papers and 44 revised poster papers together with 5 invited papers Topical sections include image filtering restoration and segmentation shape analysis and representation recognition categorization and detection computer vision and image retrieval machine learning and statistical data analysis biomedical data analysis and more **Autonomous** Driving and Advanced Driver-Assistance Systems (ADAS) Lentin Joseph, Amit Kumar Mondal, 2021-12-15 Autonomous Driving and Advanced Driver Assistance Systems ADAS Applications Development Legal Issues and Testing outlines the

latest research related to autonomous cars and advanced driver assistance systems including the development testing and verification for real time situations of sensor fusion sensor placement control algorithms and computer vision Features Co edited by an experienced roboticist and author and an experienced academic Addresses the legal aspect of autonomous driving and ADAS Presents the application of ADAS in autonomous vehicle parking systems With an infinite number of real time possibilities that need to be addressed the methods and the examples included in this book are a valuable source of information for academic and industrial researchers automotive companies and suppliers **Proceedings of 2nd International Conference on Computer Vision & Image Processing** Bidyut B. Chaudhuri, Mohan S. Kankanhalli, Balasubramanian Raman, 2018-04-11 The book provides insights into the Second International Conference on Computer Vision image video formation and display image video filtering restoration enhancement and super resolution image video coding and transmission image video storage retrieval and authentication image video quality transform based and multi resolution image video analysis biological and perceptual models for image video processing machine learning in image video analysis probability and uncertainty handling for image video processing motion and tracking segmentation and recognition shape structure and stereo Adapting Learning Techniques for Visual Recognition Hao Zhang, 2007

Computer Vision Systems: ... International Conference, ICVS ..., Proceedings, 2001 Boosting in Location Space

Damian Ryan Eads, 2011 Proceedings, 2005 Detecting and Localizing Human Figures Gregory Peter Mori, 2004

Visual Object Tracking with Doop Neural Networks Bior Luigi Marzon Spinivson Remarksishen Pools

Visual Object Tracking with Deep Neural Networks Pier Luigi Mazzeo, Srinivasan Ramakrishnan, Paolo Spagnolo,2019-12-18 Visual object tracking VOT and face recognition FR are essential tasks in computer vision with various real world applications including human computer interaction autonomous vehicles robotics motion based recognition video indexing surveillance and security This book presents the state of the art and new algorithms methods and systems of these research fields by using deep learning It is organized into nine chapters across three sections Section I discusses object detection and tracking ideas and algorithms Section II examines applications based on re identification challenges and Section III presents applications based on FR research Computer Vision - ECCV 2016 Bastian Leibe, Jiri Matas, Nicu Sebe, Max Welling, 2016-09-16 The eight volume set comprising LNCS volumes 9905 9912 constitutes the refereed proceedings of the 14th European Conference on Computer Vision ECCV 2016 held in Amsterdam The Netherlands in October 2016 The 415 revised papers presented were carefully reviewed and selected from 1480 submissions The papers cover all aspects of computer vision and pattern recognition such as 3D computer vision computational photography sensing and display face and gesture low level vision and image processing motion and tracking optimization methods physics based vision photometry and shape from X recognition detection categorization indexing matching segmentation grouping and shape representation statistical methods and learning video events activities and surveillance applications They are organized in topical sections on detection recognition and retrieval scene understanding optimization image and video

processing learning action activity and tracking 3D and 9 poster sessions Object Categorization Sven I. Dickinson, 2009-09-07 This edited volume presents a unique multidisciplinary perspective on the problem of visual object categorization. The result of a series of four highly successful workshops on the topic the book gathers many of the most distinguished researchers from both computer and human vision to reflect on their experience identify open problems and foster a cross disciplinary discussion with the idea that parallel problems and solutions have arisen in both domains Twenty seven of these workshop speakers have contributed chapters including fourteen from computer vision and thirteen from human vision Their contributions range from broad perspectives on the problem to more specific approaches collectively providing important historical context identifying the major challenges and presenting recent research results This multidisciplinary collection is the first of its kind on the topic of object categorization providing an outstanding context for graduate students and researchers in both computer and human vision Computer Vision Systems Mei Chen, Bastian Leibe, Bernd Neumann, 2013-07-11 This book constitutes the refereed proceedings of the 9th International Conference on Computer Vision Systems ICVS 2013 held in St Petersburg Russia July 16 18 2013 Proceedings The 16 revised papers presented with 20 poster papers were carefully reviewed and selected from 94 submissions. The papers are organized in topical sections on image and video capture visual attention and object detection self localization and pose estimation motion and tracking 3D reconstruction features learning and validation Computer Vision - ECCV 2016 Bastian Leibe, Jiri Matas, Nicu Sebe, Max Welling, 2016-09-16 The eight volume set comprising LNCS volumes 9905 9912 constitutes the refereed proceedings of the 14th European Conference on Computer Vision ECCV 2016 held in Amsterdam The Netherlands in October 2016 The 415 revised papers presented were carefully reviewed and selected from 1480 submissions The papers cover all aspects of computer vision and pattern recognition such as 3D computer vision computational photography sensing and display face and gesture low level vision and image processing motion and tracking optimization methods physics based vision photometry and shape from X recognition detection categorization indexing matching segmentation grouping and shape representation statistical methods and learning video events activities and surveillance applications They are organized in topical sections on detection recognition and retrieval scene understanding optimization image and video processing learning action activity and tracking 3D and 9 poster sessions Visual Object Recognition Noelia Carrillo-Donate, 1998

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