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Fanuc Robot M-10iA/10S

Short arm version – Payload up to 10 kg, reach 1098 mm



The M-10iA/10S is FANUC Robotics' latest-generation, six-axis, high performance industrial robot. This small but mighty robot only weighs 130 kg but provides 10 kg payload with the highest wrist moments and inertia in its class. Dress-out and routing of cables and airlines have been greatly simplified with a 50-mm hollow wrist and upper arm, helping to reduce system cost and improving reliability. The M-10iA/10S can be floor or wall mounted at any angle, or ceiling mounted. J3 can also flip over allowing the robot to work behind itself creating a very large work envelope. Along with FANUC's integrated vision package in the controller called iRVision™, the M-10iA/10S comes vision ready with a 2D vision cable integrated through the robot arm as a standard option.

The robot M-10iA/10S has the highest axis speeds and the best repeatability in its class, making for an extremely fast and highly repeatable robot. The M-10iA/10S is setting

the industry standard for small robots and is the perfect solution for your application.

M-10iA Series, the solution for:

- Painting and dispensing
- Material handling
- Material removal
- Assembly
- Picking and packing

Features and benefits:

- 6 degrees of freedom
- ± 0.05 mm repeatability
- 10 kg payload at wrist
- Large wrist moments and inertia for real-world I/O's and workpieces
- Supplementary payload mount on J3 casting
- 2D vision cables from J1 to J3 as a standard option
- Compact size, slim wrist, and small footprint permit operation in tight work spaces
- Robot can be floor, angle, wall or ceiling mounted
- High joint speeds maximize throughput
- Absolute encoder positioning eliminates homing at power-up
- Intelligent colourgraphic teach pendant is network ready
- Built-in solution arm, 50mm hollow wrist and upper arm

Reliability

- RV reducer, gear and harmonic drivetrains provide rigidity and performance in a compact package
- Sealed bearings and brushless, maintenance-free AC motors provide protection and improve reliability

Robot and Controller Options

- iRVision for guidance and inspection
- Up to 40 axes (robot + auxiliary) on same controller
- Extended communications capabilities: FTP, ProNet, FANUC Model A I/O rack, etc.
- Linear or circular conveyor tracking
- Many unique robot and application-driven software options available

User Manual Fanuc Robotics

Stephan Hussmann

A red circular graphic with a gradient, appearing as a semi-circle or a partial circle, located to the right of the author's name.

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Handbook of Industrial Robotics Shimon Y. Nof, 1999-03-02 About the Handbook of Industrial Robotics Second Edition Once again the Handbook of Industrial Robotics in its Second Edition explains the good ideas and knowledge that are needed for solutions Christopher B Galvin Chief Executive Officer Motorola Inc The material covered in this Handbook reflects the new generation of robotics developments It is a powerful educational resource for students engineers and managers written by a leading team of robotics experts Yukio Hasegawa Professor Emeritus Waseda University Japan The Second Edition of the Handbook of Industrial Robotics organizes and systematizes the current expertise of industrial robotics and its forthcoming capabilities These efforts are critical to solve the underlying problems of industry This continuation is a source of power I believe this Handbook will stimulate those who are concerned with industrial robots and motivate them to be great contributors to the progress of industrial robotics Hiroshi Okuda President Toyota Motor Corporation This Handbook describes very well the available and emerging robotics capabilities It is a most comprehensive guide including valuable information for both the providers and consumers of creative robotics applications Donald A Vincent Executive Vice President Robotic Industries Association 120 leading experts from twelve countries have participated in creating this Second Edition of the Handbook of Industrial Robotics Of its 66 chapters 33 are new covering important new topics in the theory design control and applications of robotics Other key features include a larger glossary of robotics terminology with over 800 terms and a CD ROM that vividly conveys the colorful motions and intelligence of robotics With contributions from the most prominent names in robotics worldwide the Handbook remains the essential resource on all aspects of this complex subject

Intelligent Control, Robotics, and Industrial Automation Sanjay Sharma, Bidyadhar Subudhi, Umesh Kumar Sahu, 2023-11-17 This volume comprises peer reviewed proceedings of the International Conference on Robotics Control Automation and Artificial Intelligence RCAAI 2022 It aims to provide a broad spectrum picture of the state of art research and development in the areas of intelligent control the Internet of Things machine vision cybersecurity robotics circuits and sensors among others This volume will provide a valuable resource for those in academia and industry **Vehicle and Automotive Engineering 4** Károly Jármay, Ákos Cservedák, 2022-09-09 This book presents the selected proceedings of the third fourth Vehicle and Automotive Engineering conference reflecting the outcomes of theoretical and practical studies and outlining future development trends in a broad field of automotive research The conference's main themes included design manufacturing economic and educational topics **Robotic Welding, Intelligence and Automation** Tzyh-Jong Tarn, Shan-Ben Chen, Xiao-Qi Chen, 2015-07-15 The primary aim of this volume is to provide researchers and engineers from both academic and industry with up to date coverage of new results in the field of robotic welding intelligent systems and automation The book is mainly based on papers selected from the 2014 International Conference on Robotic Welding Intelligence and Automation RWIA 2014 held Oct 25 27 2014 at Shanghai China The articles show that the intelligentized

welding manufacturing IWM is becoming an inevitable trend with the intelligentized robotic welding as the key technology The volume is divided into four logical parts Intelligent Techniques for Robotic Welding Sensing of Arc Welding Processing Modeling and Intelligent Control of Welding Processing as well as Intelligent Control and its Applications in Engineering

Introduction to Robotics Saeed B. Niku, 2010-09-22 Now in its second edition Introduction to Robotics is intended for senior and introductory graduate courses in robotics Designed to meet the needs of different readers this book covers a fair amount of mechanics and kinematics including manipulator kinematics differential motions robot dynamics and trajectory planning It also covers microprocessor applications control systems vision systems sensors and actuators making the book useful to mechanical engineers electronic and electrical engineers computer engineers and engineering technologists A chapter on controls presents enough material to make the understanding of robotic controls and design accessible to those who have yet to take a course in control systems

Advances in Mechanism Design IV Jaroslav Beran, Martin Bílek, Miroslav Václavík, Petr Žabka, 2024-08-30 This book presents the latest research advances relating to machines and mechanisms Featuring papers from the XIV International Conference on the Theory of Machines and Mechanisms TMM held in Liberec Czech Republic on September 3-5 2024 it includes a selection of the most important new results and developments The book is divided into five parts representing a well balanced overview and spanning the general theory of machines and mechanisms through analysis and synthesis of planar and spatial mechanisms linkages and cams robots and manipulators dynamics of machines and mechanisms rotor dynamics computational mechanics vibration and noise in machines optimization of mechanisms and machines mechanisms of textile machines mechatronics and control and monitoring systems of machines This conference is traditionally held every four years under the auspices of the international organisation IFToMM and the Czech Society for Mechanics

Automation in Agriculture Stephan Hussmann, 2018-03-14 According to Prof D Despommier by the year 2050 nearly 80% of the earth's population will reside in urban centers Furthermore the human population will increase by about 3 billion people during the interim New land will be needed to grow enough food to feed them At present throughout the world over 80% of the land that is suitable for raising crops is in use What can be done to avoid this impending disaster One possible solution is indoor farming However not all crops can easily be moved in an indoor environment Nevertheless to secure the food supply it is necessary to increase the automation level in agriculture significantly This book intends to provide the reader with a comprehensive overview of the impact of the Fourth Industrial Revolution and automation examples in agriculture

Robotics in STEM Education Myint Swe Khine, 2017-07-10 This book describes recent approaches in advancing STEM education with the use of robotics innovative methods in integrating robotics in school subjects engaging and stimulating students with robotics in classroom based and out of school activities and new ways of using robotics as an educational tool to provide diverse learning experiences It addresses issues and challenges in generating enthusiasm among students and revamping curricula to provide application focused and hands on

approaches in learning The book also provides effective strategies and emerging trends in using robotics designing learning activities and how robotics impacts the students interests and achievements in STEM related subjects The frontiers of education are progressing very rapidly This volume brought together a collection of projects and ideas which help us keep track of where the frontiers are moving This book ticks lots of contemporary boxes STEM robotics coding and computational thinking among them Most educators interested in the STEM phenomena will find many ideas in this book which challenge provide evidence and suggest solutions related to both pedagogy and content Regular reference to 21st Century skills achieved through active collaborative learning in authentic contexts ensures the enduring usefulness of this volume John Williams Professor of Education and Director of the STEM Education Research Group Curtin University Perth Australia

Advances in Italian Mechanism Science Giuseppe Quaglia, Giovanni Boschetti, Giuseppe Carbone, 2024-08-01 This book presents the proceedings of the 5th International Conference of IFToMM ITALY IFIT held in Turin Italy on September 11 13 2024 It includes peer reviewed papers on the latest advances in mechanism and machine science discussing topics such as biomechanical engineering computational kinematics the history of mechanism and machine science gearing and transmissions multi body dynamics robotics and mechatronics the dynamics of machinery tribology vibrations rotor dynamics and vehicle dynamics A valuable up to date resource it offers an essential overview of the subject for scientists and practitioners alike and inspires further investigations and research *Instrument Engineers' Handbook, Volume 3* Bela G. Liptak, Halit Eren, 2018-10-08 Instrument Engineers Handbook Volume 3 Process Software and Digital Networks Fourth Edition is the latest addition to an enduring collection that industrial automation AT professionals often refer to as the bible First published in 1970 the entire handbook is approximately 5 000 pages designed as standalone volumes that cover the measurement Volume 1 control Volume 2 and software Volume 3 aspects of automation This fourth edition of the third volume provides an in depth state of the art review of control software packages used in plant optimization control maintenance and safety Each updated volume of this renowned reference requires about ten years to prepare so revised installments have been issued every decade taking into account the numerous developments that occur from one publication to the next Assessing the rapid evolution of automation and optimization in control systems used in all types of industrial plants this book details the wired wireless communications and software used This includes the ever increasing number of applications for intelligent instruments enhanced networks Internet use virtual private networks and integration of control systems with the main networks used by management all of which operate in a linked global environment Topics covered include Advances in new displays which help operators to more quickly assess and respond to plant conditions Software and networks that help monitor control and optimize industrial processes to determine the efficiency energy consumption and profitability of operations Strategies to counteract changes in market conditions and energy and raw material costs Techniques to fortify the safety of plant operations and the security of digital communications systems This volume explores

why the holistic approach to integrating process and enterprise networks is convenient and efficient despite associated problems involving cyber and local network security energy conservation and other issues It shows how firewalls must separate the business IT and the operation automation technology or AT domains to guarantee the safe function of all industrial plants This book illustrates how these concerns must be addressed using effective technical solutions and proper management policies and practices Reinforcing the fact that all industrial control systems are in general critically interdependent this handbook provides a wide range of software application examples from industries including automotive mining renewable energy steel dairy pharmaceutical mineral processing oil gas electric power utility and nuclear power

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Table of Contents User Manual Fanuc Robotics

1. Understanding the eBook User Manual Fanuc Robotics
 - The Rise of Digital Reading User Manual Fanuc Robotics
 - Advantages of eBooks Over Traditional Books
2. Identifying User Manual Fanuc Robotics
 - Exploring Different Genres
 - Considering Fiction vs. Non-Fiction
 - Determining Your Reading Goals
3. Choosing the Right eBook Platform
 - Popular eBook Platforms
 - Features to Look for in an User Manual Fanuc Robotics
 - User-Friendly Interface
4. Exploring eBook Recommendations from User Manual Fanuc Robotics
 - Personalized Recommendations
 - User Manual Fanuc Robotics User Reviews and Ratings
 - User Manual Fanuc Robotics and Bestseller Lists
5. Accessing User Manual Fanuc Robotics Free and Paid eBooks
 - User Manual Fanuc Robotics Public Domain eBooks
 - User Manual Fanuc Robotics eBook Subscription Services
 - User Manual Fanuc Robotics Budget-Friendly Options

6. Navigating User Manual Fanuc Robotics eBook Formats
 - ePub, PDF, MOBI, and More
 - User Manual Fanuc Robotics Compatibility with Devices
 - User Manual Fanuc Robotics Enhanced eBook Features
7. Enhancing Your Reading Experience
 - Adjustable Fonts and Text Sizes of User Manual Fanuc Robotics
 - Highlighting and Note-Taking User Manual Fanuc Robotics
 - Interactive Elements User Manual Fanuc Robotics
8. Staying Engaged with User Manual Fanuc Robotics
 - Joining Online Reading Communities
 - Participating in Virtual Book Clubs
 - Following Authors and Publishers User Manual Fanuc Robotics
9. Balancing eBooks and Physical Books User Manual Fanuc Robotics
 - Benefits of a Digital Library
 - Creating a Diverse Reading Collection User Manual Fanuc Robotics
10. Overcoming Reading Challenges
 - Dealing with Digital Eye Strain
 - Minimizing Distractions
 - Managing Screen Time
11. Cultivating a Reading Routine User Manual Fanuc Robotics
 - Setting Reading Goals User Manual Fanuc Robotics
 - Carving Out Dedicated Reading Time
12. Sourcing Reliable Information of User Manual Fanuc Robotics
 - Fact-Checking eBook Content of User Manual Fanuc Robotics
 - Distinguishing Credible Sources
13. Promoting Lifelong Learning
 - Utilizing eBooks for Skill Development
 - Exploring Educational eBooks
14. Embracing eBook Trends
 - Integration of Multimedia Elements

- Interactive and Gamified eBooks

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