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Wenbin Ji



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Proceedings of the 5th China Aeronautical Science and Technology Conference Chinese Aeronautical Society, 2021-11-02 To sort out the progress of aviation science and technology and industry look forward to the future development trend commend scientific and technological innovation achievements and talents strengthen international cooperation promote discipline exchanges encourage scientific and technological innovation and promote the development of aviation the Chinese Aeronautical Society holds a China Aviation Science and Technology Conference every two years which has been successfully held for four times and has become the highest level largest scale most influential and authoritative science and technology conference in the field of aviation in China The 5th China Aviation Science and Technology Conference will be held in Wuzhen Jiaxing City Zhejiang Province in 2021 with the theme of New Generation of Aviation Equipment and Technology with academican Zhang Yanzhong as the chairman of the conference This book contains original peer reviewed research papers from the conference The topics covered include but are not limited to navigation guidance and control technologies key technologies for aircraft design and overall optimization aviation test technologies aviation airborne systems electromechanical technologies structural design aerodynamics and flight mechanics other related technologies advanced aviation materials and manufacturing technologies advanced aviation propulsion technologies and civil aviation transportation The papers presented here share the latest discoveries on aviation science and technology making the book a valuable asset for researchers engineers and students

NASA Tech Briefs, 2001 DESIGN, SYNTHESIS AND CONTROL OF A MECHANICAL SERVO PRESS: AN INDUSTRIAL APPLICATION, Abstract Due to precision flexibility simplicity in construction easy control higher speed and lower energy consumptions servo presses have recently become popular in metal forming applications Servo press technology combines the advantages of hydraulic and conventional mechanical presses without their drawbacks This study presents design construction and demonstration of a servo crank press system for metal forming operations The research involves kinematics and motion optimization dynamic modeling structural design and analysis servo motor selection automation and control and operational performances of the servo press The press used in this work has a load capacity of 50 ton and stroke capacity of 200 mm Firstly optimized trajectories of ram scenarios are generated Then dynamic modeling using Lagrange approach is presented Next structural model is constructed and Finite Element Analysis FEA of press parts are performed within safety limits A servo motor with a reduction unit is selected based on dynamic model After that a new automation system is developed and Cascade Feed Forward CasFF control is applied Moreover four motion scenarios crank dwell link and soft motion are employed for the performance assessment of press Finally the dynamic model is verified by the experimental results The research study is carried out under support and grant of an industrial project aiming to provide know how to industry and researchers

Key Words Servo crank press metal forming motion design dynamic modeling system control *Advances in Reconfigurable*

Mechanisms and Robots I Jian S Dai, Matteo Zoppi, Xianwen Kong, 2012-06-13 *Advances in Reconfigurable Mechanisms and Robots I* provides a selection of key papers presented in The Second ASME IFToMM International Conference on Reconfigurable Mechanisms and Robots ReMAR 2012 held on 9th 11th July 2012 in Tianjin China This ongoing series of conferences will be covered in this ongoing collection of books A total of seventy eight papers are divided into seven parts to cover the topology kinematics and design of reconfigurable mechanisms with the reconfiguration theory analysis and synthesis and present the current research and development in the field of reconfigurable mechanisms including reconfigurable parallel mechanisms In this aspect the recent study and development of reconfigurable robots are further presented with the analysis and design and with their control and development The bio inspired mechanisms and subsequent reconfiguration are explored in the challenging fields of rehabilitation and minimally invasive surgery *Advances in Reconfigurable Mechanisms and Robots I* further extends the study to deployable mechanisms and foldable devices and introduces applications of reconfigurable mechanisms and robots The rich content of *Advances in Reconfigurable Mechanisms and Robots I* brings together new developments in reconfigurable mechanisms and robots and presents a new horizon for future development in the field of reconfigurable mechanisms and robots **Leveraging Transdisciplinary**

Engineering in a Changing and Connected World Adam Cooper, 2023-11-15 Simple problems have become rare in today's technologically advanced world Problems are typically much more complex and solving them requires integrative knowledge from several disciplines Technology alone cannot be the answer Collaborative teams equipped with knowledge and skills in various disciplines are indispensable to exploit technologies effectively and create new conceptual theoretical methodological and translational innovations that integrate and move beyond discipline specific approaches to address a common problem in the changing and connected world This book presents the proceedings of TE2023 the 30th International Conference on Transdisciplinary Engineering held in Hua Hin Cha Am Thailand from 11 14 July 2023 The theme of this year's conference was Leveraging Transdisciplinary Engineering in a Changing and Connected World and it provided a forum for more than 115 participants from academia and industry to exchange knowledge and ideas connected to this aspect of transdisciplinary engineering A total of 117 submissions were received for the conference of which 93 were selected for presentation and publication here following a rigorous abstract and full paper review process They are arranged under 7 categories product design and development team working smart operations for value chain management transdisciplinary approaches engineering education critical issues in transdisciplinary engineering and theoretical contributions Providing a comprehensive overview of the latest innovations and ideas in transdisciplinary engineering the book will be of interest to all those working in the field *Intelligent Robotics and Applications* Huayong Yang, Honghai Liu, Jun Zou, Zhouping Yin, Lianqing Liu, Geng Yang, Xiaoping Ouyang, Zhiyong Wang, 2023-10-20 The 9 volume set LNAI 14267 14275 constitutes the proceedings of the 16th International Conference on Intelligent Robotics and Applications ICIRA 2023 which took place in

Hangzhou China during July 5-7, 2023. The 413 papers included in these proceedings were carefully reviewed and selected from 630 submissions. They were organized in topical sections as follows:

Part I: Human Centric Technologies for Seamless Human Robot Collaboration, Multimodal Collaborative Perception and Fusion, Intelligent Robot Perception in Unknown Environments, Vision Based Human Robot Interaction and Application, Reliable AI on Machine Human Reactions, Wearable Sensors and Robots, Wearable Robots for Assistance Augmentation and Rehabilitation of Human Movements, Perception and Manipulation of Dexterous Hand for Humanoid Robot.

Part II: Perception and Manipulation of Dexterous Hand for Humanoid Robot, Medical Imaging for Biomedical Robotics, Advanced Underwater Robot Technologies, Innovative Design and Performance Evaluation of Robot Mechanisms, Evaluation of Wearable Robots for Assistance and Rehabilitation, 3D Printing Soft Robots.

Part III: 3D Printing Soft Robots, Dielectric Elastomer Actuators for Soft Robotics, Human like Locomotion and Manipulation, Pattern Recognition and Machine Learning for Smart Robots.

Part IV: Pattern Recognition and Machine Learning for Smart Robots, Robotic Tactile Sensation Perception and Applications, Advanced Sensing and Control Technology for Human Robot Interaction, Knowledge Based Robot Decision Making and Manipulation, Design and Control of Legged Robots.

Part V: Design and Control of Legged Robots, Robots in Tunnelling and Underground Space, Robotic Machining of Complex Components, Clinically Oriented Design in Robotic Surgery and Rehabilitation, Visual and Visual Tactile Perception for Robotics.

Part VI: Visual and Visual Tactile Perception for Robotics, Perception Interaction and Control of Wearable Robots, Marine Robotics and Applications, Multi Robot Systems for Real World Applications, Physical and Neurological Human Robot Interaction.

Part VII: Physical and Neurological Human Robot Interaction, Advanced Motion Control Technologies for Mobile Robots, Intelligent Inspection Robotics, Robotics in Sustainable Manufacturing for Carbon Neutrality, Innovative Design and Performance Evaluation of Robot Mechanisms.

Part VIII: Innovative Design and Performance Evaluation of Robot Mechanisms, Cutting Edge Research in Robotics.

AutomationML Rainer Drath, 2021-07-19. This book provides a comprehensive in depth look into the practical application of AutomationML Edition 2 from an industrial perspective. It is a cookbook for advanced users and describes reusable pattern solutions for a variety of industrial applications and how to implement it in software. Just to name some: AutomationML modelling of AAS, MTP, SCD, OPC UA, Automation Components, Automation Projects, drive configurations, requirement models, communication systems, electrical interfaces and cables or semantic integration aspects as eClass integration or handling of semantic heterogeneity. This book guides through the universe of AutomationML from industrial perspective. It is written by AutomationML experts that have industrially implemented AutomationML in pattern solutions for a large variety of applications. This book is structured into three major parts: Part I: software implementation for developers, Part II: reusable industrial pattern solutions and domain models, Part III: outlook into future AutomationML applications. Additional material to the book and more information about AutomationML on the website <https://www.automationml.org> about automationml publications amlbook.

SPS2022 Amos H.C. Ng, Anna Syberfeldt, Magnus Holm, 2022-05-15 The realization of a successful product requires collaboration between developers and producers taking account of stakeholder value reinforcing the contribution of industry to society and enhancing the wellbeing of workers while respecting planetary boundaries Founded in 2006 the Swedish Production Academy SPA aims to drive and develop production research and education and to increase cooperation within the production area This book presents the proceedings of the 10th Swedish Production Symposium SPS2022 held in Skövde Sweden from 26-29 April 2022 The overall theme of the symposium was Industry 5.0 Transformation Towards a Sustainable Human Centric and Resilient Production Since its inception in 2007 the purpose of SPS has been to facilitate an event at which members and interested participants from industry and academia can meet to exchange ideas The 69 papers accepted for presentation here are grouped into ten sections resource efficient production flexible production humans in the production system circular production systems and maintenance integrated product and production development industrial optimization and decision making cyber physical production systems and digital twins innovative production processes and additive manufacturing smart and resilient supply chains and linking research and education Also included are three sections covering the Special Sessions at SPS2022 artificial intelligence and industrial analytics in industry 4.0 development of resilient and sustainable production systems and boundary crossing and boundary objects in product and production development The book will be of interest to all those involved in the development and production of future products

Towards Energy Transparent Factories Gerrit Posselt, 2015-08-01 This monograph provides a methodological approach for establishing demand oriented levels of energy transparency of factories The author presents a systematic indication of energy drivers and cost factors taking into account the interdependencies between facility and production domains Particular attention is given to energy flow metering and monitoring Readers will also be provided with an in depth description of a planning tool which allows for systematically deriving suitable metering points in complex factory environments The target audience primarily comprises researchers and experts in the field of factory planning but the book may also be beneficial for graduate students

Production at the Leading Edge of Technology Mathias Liewald, Alexander Verl, Thomas Bauernhansl, Hans-Christian Möhring, 2023-02-01 The German Academic Association for Production Technology WGP annually invites researchers coming from its institutes and from industry to contribute peer reviewed papers in the field of production technology This congress proceedings provides recent research results and findings on leading edge manufacturing processes Main aim of this scientific congress is to push forward existing borders in production and to provide novel solutions of Production at the Leading Edge of Manufacturing Technology Different sessions were held on the topics Recent Developments in Manufacturing Processes Advancements in Production Planning New Approaches in Machine Learning Aspects of Resilience of Production Processes Creating Digital Twins for Production

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