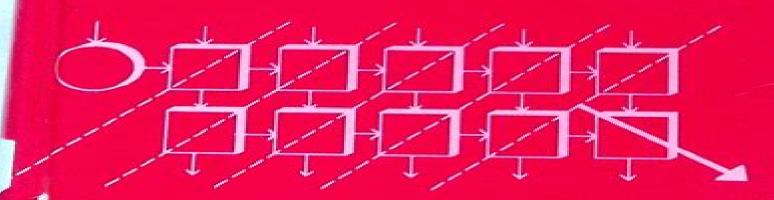


TRANSPUTERS in REAL-TIME CONTROL

G. W. Irwin P. J. Fleming



Transputers In Real Time Control Industrial Control Computers And Communication Series

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Transputers in Real-Time Control G. W. Irwin, P. J. Fleming, 1992-12-08 Describes applications of the transputer for real time control across the spectrum of engineering The text concentrates on transputer architecture and real time control with a strong emphasis on case studies and practical applications in many fields of engineering Transputers in Real-time Control George William Irwin, Peter J. Fleming, 1992 Algorithms and Architectures for Real-Time Control 1992 P.J. Fleming, W.H. Kwon, 2014-05-23 This Workshop focuses on such issues as control algorithms which are suitable for real time use computer architectures which are suitable for real time control algorithms and applications for real time control issues in the areas of parallel algorithms multiprocessor systems neural networks fault tolerance systems real time robot control identification real time filtering algorithms control algorithms fuzzy control adaptive and self tuning control and real time control applications **Real-time Systems with Transputers** Occam User Group. Technical Meeting, 1990 **Computing and Transputers** D. Arnold, 1994 The broadening of interest in parellel computing and transputers is reflected in this text Topics covered include concurrent programming graphics and image processing and robotics and control It is based on the proceedings of the 6th Australian Transputer and Occam User Group **Algorithms and Architectures for** Real-Time Control 1991 P.J. Fleming, D.I. Jones, 2014-07-22 Computer scientists have long appreciated that the relationship between algorithms and architecture is crucial Broadly speaking the more specialized the architecture is to a particular algorithm then the more efficient will be the computation The penalty is that the architecture will become useless for computing anything other than that algorithm This message holds for the algorithms used in real time automatic control as much as any other field These Proceedings will provide researchers in this field with a useful up to date reference source of recent developments Transputer Applications and Systems '94 A. De Gloria, M. R. Jane, D. Marini, 1994 Proceedings Parallel Computing **European Optical Communications and Networks** ,1994 Advanced Guided Vehicles: Aspects Of The Oxford Agy Project Stephen Cameron, Penelope Probert Smith, 1994-10-10 The Oxford University Robotics Research Group has been working for several years to improve the ability of automated guided vehicles This book brings together much of the key research work on sensors and planning that was inspired by an industrial vehicle donated by a factory automation division in GEC GEC FAST together with background material to provide a basic but up to date reference guide to autonomous vehicle research The book includes work on control sensing technologies sensor management and data fusion different styles of path planning suited for off line or online plans and task planning It is designed to act both as a reference for the robotics professional and as a text for university level courses Signal ,1990

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