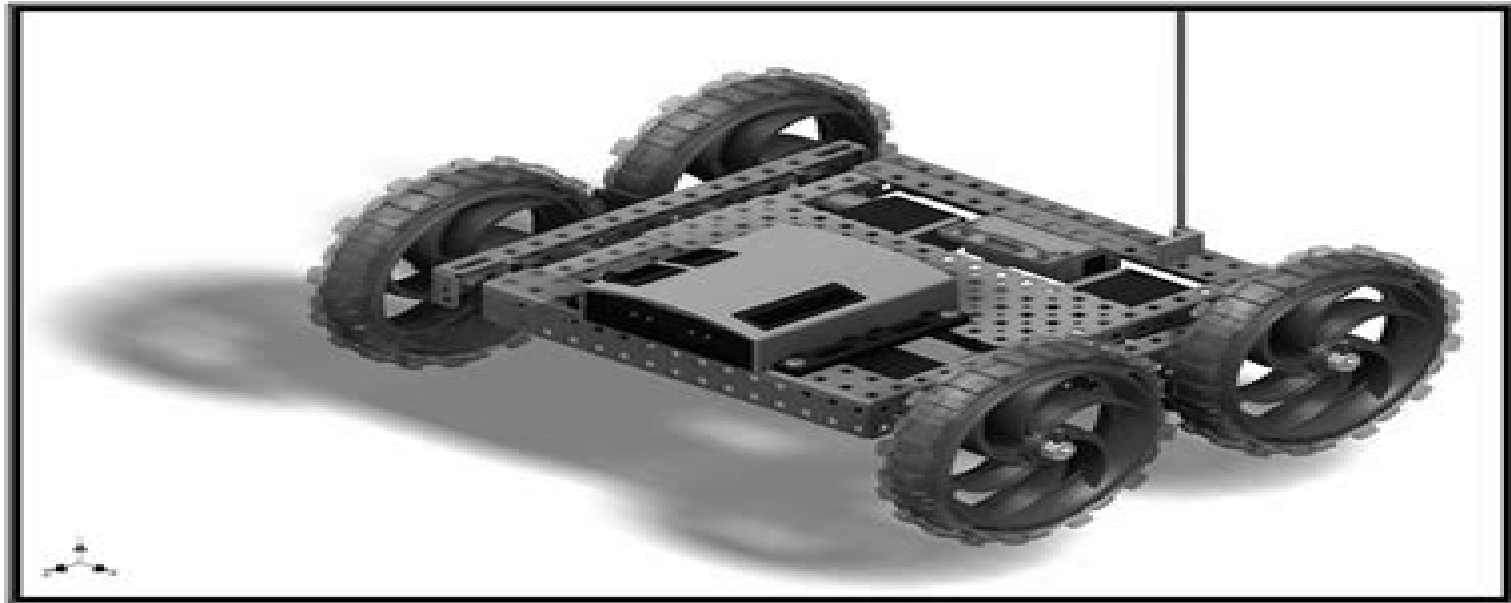


Tools for Design

with VEX Robot Kit:

AutoCAD® 2011 and Autodesk® Inventor® 2011

2D Drawing ❖ 3D Modeling ❖ Hand Sketching



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Tools for Design With Vex Robot Kit Randy Shih, 2010-10-12 Tools for Design is intended to provide the user with an overview of computer aided design using two popular CAD software packages from Autodesk AutoCAD and Autodesk Inventor This book explores the strengths of each package and show how they can be used in design both separately and in combination with each other What you ll learn How to create and dimension 2D multiview drawings using AutoCAD How to freehand sketch using axonometric oblique and perspective projection techniques How to create 3D parametric models and 2D multiview drawings using Autodesk Inventor How to reuse design information between AutoCAD and Autodesk Inventor How to combine parts into assemblies including assembly modeling with a VEX Robot Kit How to perform basic finite element stress analysis using Inventor Stress Analysis Module

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mechanisms commonly used in walking robots You will learn the basic types of planar four bar linkages commonly used in mechanical designs and how to use the GeoGebra Dynamic Geometry software to simulate and analyze 2D linkages Using the knowledge you gained about linkages and mechanism you will learn how to modify your robot and change its behavior by modifying or creating new parts In the final chapter of this book you learn how to combine all the robot parts into assemblies and then run motion analysis You will finish off your project by creating 3D animations of your robot in action There are many books that show you how to perform individual tasks with Autodesk Inventor but this book takes you through an entire project and shows you the complete engineering process By the end of this book you will have modeled and assembled nearly all the parts that make up the TAMIYA Mechanical Tiger and can start building your own robot **Engineering Design**

Graphics with Autodesk Inventor 2011 James D. Bethune, 2012 Using a step by step format Engineering Design Graphics with Autodesk Inventor 2011 shows students how to use Autodesk Inventor to create and document designs Chapter test questions help students assess their understanding of key concepts Sample problems end of chapter projects and a variety of additional exercises reinforce the material and allow students to practice the techniques described The content of the book goes beyond the material normally presented in an engineering graphics text associated with CAD software to include exercises requiring students to design simple mechanisms Learning Autodesk Inventor 2024 Randy Shih, 2023 Teaches beginners how to use Autodesk Inventor with easy to understand tutorials Features a simple robot design used as a project throughout the book Covers modeling gear creation linkage analysis assemblies simulations and 3D animation Available with an optional robot kit This book will teach you everything you need to know to start using Autodesk Inventor 2024 with easy to understand step by step tutorials This book features a simple robot design used as a project throughout the book You will learn to model parts create assemblies run simulations and even create animations of your robot design An unassembled version of the same robot used throughout the book can be bundled with the book No previous experience with Computer Aided Design CAD is needed since this book starts at an introductory level The author begins by getting you familiar with the Inventor interface and its basic tools You will start by learning to model simple robot parts and before long you will graduate to creating more complex parts and multi view drawings Along the way you will learn the fundamentals of parametric modeling through the use of geometric constraints and relationships You will also become familiar with many of Inventor's powerful tools and commands that enable you to easily construct complex features in your models Also included is coverage of gears gear trains and spur gear creation using Autodesk Inventor This book continues by examining the different mechanisms commonly used in walking robots You will learn the basic types of planar four bar linkages commonly used in mechanical designs and how to use the GeoGebra Dynamic Geometry software to simulate and analyze 2D linkages Using the knowledge you gained about linkages and mechanism you will learn how to modify your robot and change its behavior by modifying or creating new parts In the final chapter of this book you learn how to combine all the robot parts into assemblies

and then run motion analysis You will finish off your project by creating 3D animations of your robot in action There are many books that show you how to perform individual tasks with Autodesk Inventor but this book takes you through an entire project and shows you the complete engineering process By the end of this book you will have modeled and assembled nearly all the parts that make up the TAMIYA Mechanical Tiger and can start building your own robot *Learning Autodesk Inventor 2022* Randy Shih,2021-08 This book will teach you everything you need to know to start using Autodesk Inventor 2022 with easy to understand step by step tutorials This book features a simple robot design used as a project throughout the book You will learn to model parts create assemblies run simulations and even create animations of your robot design An unassembled version of the same robot used throughout the book can be bundled with the book No previous experience with Computer Aided Design CAD is needed since this book starts at an introductory level The author begins by getting you familiar with the Inventor interface and its basic tools You will start by learning to model simple robot parts and before long you will graduate to creating more complex parts and multi view drawings Along the way you will learn the fundamentals of parametric modeling through the use of geometric constraints and relationships You will also become familiar with many of Inventor s powerful tools and commands that enable you to easily construct complex features in your models Also included is coverage of gears gear trains and spur gear creation using Autodesk Inventor This book continues by examining the different mechanisms commonly used in walking robots You will learn the basic types of planar four bar linkages commonly used in mechanical designs and how to use the GeoGebra Dynamic Geometry software to simulate and analyze 2D linkages Using the knowledge you gained about linkages and mechanism you will learn how to modify your robot and change its behavior by modifying or creating new parts In the final chapter of this book you learn how to combine all the robot parts into assemblies and then run motion analysis You will finish off your project by creating 3D animations of your robot in action There are many books that show you how to perform individual tasks with Autodesk Inventor but this book takes you through an entire project and shows you the complete engineering process By the end of this book you will have modeled and assembled nearly all the parts that make up the TAMIYA Mechanical Tiger and can start building your own robot *Learning Autodesk Inventor 2020* Randy Shih,2019-07 This book will teach you everything you need to know to start using Autodesk Inventor 2020 with easy to understand step by step tutorials This book features a simple robot design used as a project throughout the book You will learn to model parts create assemblies run simulations and even create animations of your robot design An unassembled version of the same robot used throughout the book can be bundled with the book No previous experience with Computer Aided Design CAD is needed since this book starts at an introductory level The author begins by getting you familiar with the Inventor interface and its basic tools You will start by learning to model simple robot parts and before long you will graduate to creating more complex parts and multi view drawings Along the way you will learn the fundamentals of parametric modeling through the use of geometric constraints and relationships You will also become familiar with many of

Inventor's powerful tools and commands that enable you to easily construct complex features in your models. Also included is coverage of gears, gear trains, and spur gear creation using Autodesk Inventor. This book continues by examining the different mechanisms commonly used in walking robots. You will learn the basic types of planar four-bar linkages commonly used in mechanical designs and how to use the GeoGebra Dynamic Geometry software to simulate and analyze 2D linkages. Using the knowledge you gained about linkages and mechanism, you will learn how to modify your robot and change its behavior by modifying or creating new parts. In the final chapter of this book, you learn how to combine all the robot parts into assemblies and then run motion analysis. You will finish off your project by creating 3D animations of your robot in action. There are many books that show you how to perform individual tasks with Autodesk Inventor, but this book takes you through an entire project and shows you the complete engineering process. By the end of this book, you will have modeled and assembled nearly all the parts that make up the TAMIYA Mechanical Tiger and can start building your own robot. **Learning Autodesk**

Inventor 2014 Randy Shih, 2013-05-30 This book will teach you everything you need to know to start using Autodesk Inventor 2014 with easy-to-understand step-by-step tutorials. This book features a simple robot design used as a project throughout the book. You will learn to model parts, create assemblies, run simulations, and even create animations of your robot design. An unassembled version of the same robot used throughout the book can be bundled with the book. No previous experience with Computer Aided Drafting (CAD) is needed since this book starts at an introductory level. The author begins by getting you familiar with the Inventor interface and its basic tools. You will start by learning to model simple robot parts, and before long, you will graduate to creating more complex parts and multi-view drawings. Along the way, you will learn the fundamentals of parametric modeling through the use of geometric constraints and relationships. You will also become familiar with many of Inventor's powerful tools and commands that enable you to easily construct complex features in your models. Also included is coverage of gears, gear trains, and spur gear creation using Autodesk Inventor. This book continues by examining the different mechanisms commonly used in walking robots. You will learn the basic types of planar four-bar linkages commonly used in mechanical designs and how to use the GeoGebra Dynamic Geometry software to simulate and analyze 2D linkages. Using the knowledge you gained about linkages and mechanism, you will learn how to modify your robot and change its behavior by modifying or creating new parts. In the final chapter of this book, you learn how to combine all the robot parts into assemblies and then run motion analysis. You will finish off your project by creating 3D animations of your robot in action. There are many books that show you how to perform individual tasks with Autodesk Inventor, but this book takes you through an entire project and shows you the complete engineering process. By the end of this book, you will have modeled and assembled nearly all the parts that make up the TAMIYA Mechanical Tiger and can start building your own robot. *Learning Autodesk Inventor 2023* Randy Shih, 2022-07 This book will teach you everything you need to know to start using Autodesk Inventor 2023 with easy-to-understand step-by-step tutorials. This book features a simple robot design

used as a project throughout the book You will learn to model parts create assemblies run simulations and even create animations of your robot design An unassembled version of the same robot used throughout the book can be bundled with the book No previous experience with Computer Aided Design CAD is needed since this book starts at an introductory level The author begins by getting you familiar with the Inventor interface and its basic tools You will start by learning to model simple robot parts and before long you will graduate to creating more complex parts and multi view drawings Along the way you will learn the fundamentals of parametric modeling through the use of geometric constraints and relationships You will also become familiar with many of Inventor s powerful tools and commands that enable you to easily construct complex features in your models Also included is coverage of gears gear trains and spur gear creation using Autodesk Inventor This book continues by examining the different mechanisms commonly used in walking robots You will learn the basic types of planar four bar linkages commonly used in mechanical designs and how to use the GeoGebra Dynamic Geometry software to simulate and analyze 2D linkages Using the knowledge you gained about linkages and mechanism you will learn how to modify your robot and change its behavior by modifying or creating new parts In the final chapter of this book you learn how to combine all the robot parts into assemblies and then run motion analysis You will finish off your project by creating 3D animations of your robot in action There are many books that show you how to perform individual tasks with Autodesk Inventor but this book takes you through an entire project and shows you the complete engineering process By the end of this book you will have modeled and assembled nearly all the parts that make up the TAMIYA Mechanical Tiger and can start building your own robot

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