From Continuous to Hybrid System Verification

1. Find states that can be reached despite disturbances $\dot{x}(t) \in Ax(t) + BU + CV$ in which V is set of disturbances

2. Find reach set of hybrid systems $\dot{x}(t) \in A_i x(t) + B_i U$

in which i-th system is triggered by 'guard'

$$\langle c_i, x
angle = d_i$$
 (future work)

Verification And Control Of Hybrid Systems Verification And Control Of Hybrid Systems

Edmund M. Clarke, Thomas A. Henzinger, Helmut Veith, Roderick Bloem

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physical world via sensors and actuators in a feedback loop Increasingly such systems are everywhere from smart buildings to medical devices to automobiles This textbook offers a rigorous and comprehensive introduction to the principles of design specification modeling and analysis of cyber physical systems. The book draws on a diverse set of subdisciplines including model based design concurrency theory distributed algorithms formal methods of specification and verification control theory real time systems and hybrid systems explaining the core ideas from each that are relevant to system design and analysis The book explains how formal models provide mathematical abstractions to manage the complexity of a system design It covers both synchronous and asynchronous models for concurrent computation continuous time models for dynamical systems and hybrid systems for integrating discrete and continuous evolution. The role of correctness requirements in the design of reliable systems is illustrated with a range of specification formalisms and the associated techniques for formal verification The topics include safety and liveness requirements temporal logic model checking deductive verification stability analysis of linear systems and real time scheduling algorithms Principles of modeling specification and analysis are illustrated by constructing solutions to representative design problems from distributed algorithms network protocols control design and robotics This book provides the rapidly expanding field of cyber physical systems with a long needed foundational text by an established authority It is suitable for classroom use or as a reference for professionals Formal Techniques for Networked and Distributed Systems ,2001 Hybrid Dynamical Systems Hai Lin, Panos J. Antsaklis, Now Publishers, 2014 Hybrid dynamical systems are a class of complex systems that involve interacting discrete event and continuous variable dynamics They are important in applications in embedded systems cyber physical systems robotics manufacturing systems traffic management biomolecular networks and have recently been at the center of intense research activity in the control theory computer aided verification and artificial intelligence communities This paper provides a tutorial introduction to this multidisciplinary research area A number of fundamental topics such as modeling abstraction verification supervisory control stability analysis stabilization and optimal control of hybrid systems are introduced and discussed Additionally more advanced topics are briefly discussed at the end of each chapter with references given for further reading Algebraic Integrated Formal Methods Erika Ábrahám, Marieke Methodology and Software Technology, 2000 Huisman, 2016-05-23 This book constitutes the refereed proceedings of the 12th International Conference on Integrated Formal Methods IFM 2016 held in Reykjavik Iceland in June 2016 The 33 papers presented in this volume were carefully reviewed and selected from 99 submissions They were organized in topical sections named invited contributions program verification probabilistic systems concurrency safety and liveness model learning SAT and SMT solving testing theorem proving and constraint satisfaction case studies FM ... Formal Methods ,1999 **Control and Verification of** Industrial Hybrid Systems Using Models Specified with the Formalism \$ \chi \$ J. J. H. Fey, 1996 SIAM Journal on Control and Optimization Society for Industrial and Applied Mathematics, 2008

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