



VIEW-BASED 3-D OBJECT RETRIEVAL

YUE SAI | QIONGHAI DU

View Based 3 D Object Retrieval Qionghai Dai

**Tobias Schreck, Maximilian
Scherer, Michael Walter, Benjamin
Bustos, Sang Min Yoon, Arjan Kuijper**



View Based 3 D Object Retrieval Qionghai Dai:

View-based 3-D Object Retrieval Yue Gao,Qionghai Dai,2014-12-04 Content based 3 D object retrieval has attracted extensive attention recently and has applications in a variety of fields such as computer aided design tele medicine mobile multimedia virtual reality and entertainment The development of efficient and effective content based 3 D object retrieval techniques has enabled the use of fast 3 D reconstruction and model design Recent technical progress such as the development of camera technologies has made it possible to capture the views of 3 D objects As a result view based 3 D object retrieval has become an essential but challenging research topic View based 3 D Object Retrieval introduces and discusses the fundamental challenges in view based 3 D object retrieval proposes a collection of selected state of the art methods for accomplishing this task developed by the authors and summarizes recent achievements in view based 3 D object retrieval Part I presents an Introduction to View based 3 D Object Retrieval Part II discusses View Extraction Selection and Representation Part III provides a deep dive into View Based 3 D Object Comparison and Part IV looks at future research and developments including Big Data application and geographical location based applications Systematically introduces view based 3 D object retrieval including problem definitions and settings methodologies and benchmark testing beds Discusses several key challenges in view based 3 D object retrieval and introduces the state of the art solutions Presents the progression from general image retrieval techniques to view based 3 D object retrieval Introduces future research efforts in the areas of Big Data feature extraction and geographical location based applications Hypergraph Computation Qionghai Dai,Yue Gao,2023-06-16 This open access book discusses the theory and methods of hypergraph computation Many underlying relationships among data can be represented using graphs for example in the areas including computer vision molecular chemistry molecular biology etc In the last decade methods like graph based learning and neural network methods have been developed to process such data they are particularly suitable for handling relational learning tasks In many real world problems however relationships among the objects of our interest are more complex than pair wise Naively squeezing the complex relationships into pairwise ones will inevitably lead to loss of information which can be expected valuable for learning tasks Hypergraph as a generation of graph has shown superior performance on modelling complex correlations compared with graph Recent years have witnessed a great popularity of researches on hypergraph related AI methods which have been used in computer vision social media analysis etc We summarize these attempts as a new computing paradigm called hypergraph computation which is to formulate the high order correlations underneath the data using hypergraph and then conduct semantic computing on the hypergraph for different applications The content of this book consists of hypergraph computation paradigms hypergraph modelling hypergraph structure evolution hypergraph neural networks and applications of hypergraph computation in different fields We further summarize recent achievements and future directions on hypergraph computation in this book Computer-Aided Glaucoma Diagnosis System Arwa Ahmed Gasm Elseid,Alnazier

Osman Mohammed Hamza,2020-05-14 Glaucoma is the second leading cause of blindness globally Early detection and treatment can prevent its progression to avoid total blindness This book discusses and reviews current approaches for detection and examines new approaches for diagnosing glaucoma using CAD system Computer Aided Glaucoma Diagnosis System Chapter 1 provides a brief introduction of the disease and current methodology used to diagnose it today Chapter 2 presents a review of the medical background of the disease followed by a theoretical and mathematical background used in fundus image processing Chapter 3 is a literature review about segmentation and feature extraction Chapter 4 describes the formulation of the proposed methodology In Chapter 5 the results of optic disc and optic cup segmentation algorithm are presented the feature extraction and selection method experimental results and performance evaluations of the classifier are given Chapter 6 presents the conclusions and discussion of the future potential for the diagnostic system This book is intended for biomedical engineers computer science students ophthalmologists and radiologists looking to develop a reliable automated computer aided diagnosis system CAD for detecting glaucoma and improve diagnosis of the disease Key Features Discusses a reliable automated computer aided diagnosis system CAD for detecting glaucoma and presents an algorithm that detects optic disc and optic cup Assists ophthalmologists and researchers to test a new diagnostic method that reduces the effort and time of the doctors and cost to the patients Discusses techniques to reduce human error and minimize the miss detection rate and facilitate early diagnosis and treatment Presents algorithms to detect cup and disc color shape features and RNFL texture features Dr Arwa Ahmed Gasm Elseid is an assistant professor Department of Biomedical Engineering Sudan University of Science and Technology Khartoum Sudan Dr Alnazier Osman Mohammed Hamza is professor of Medical Imaging College of Engineering Sudan University of Sciences and Technology Khartoum Sudan *Advances in Multimedia Information Processing - PCM 2018* Richang Hong,Wen-Huang Cheng,Toshihiko Yamasaki,Meng Wang,Chong-Wah Ngo,2018-09-18 The three volume set LNCS 101164 11165 and 11166 constitutes the refereed proceedings of the 19th Pacific Rim Conference on Multimedia PCM 2018 held in Hefei China in September 2018 The 209 regular papers presented together with 20 special session papers were carefully reviewed and selected from 452 submissions The papers cover topics such as multimedia content analysis multimedia signal processing and communications and multimedia applications and services **Index to IEEE Publications** Institute of Electrical and Electronics Engineers,1996 Issues for 1973 cover the entire IEEE technical literature **3D Object Retrieval** ,2010 **3D Object Retrieval and Recognition** Boqing Gong,2010 **Content-Based 3D Object Retrieval** ,2008 *Efficient 3D Object Retrieval Using Depth Images* Nikhil Vajramushti,2004 *Shape Distinction for 3d Object Retrieval* Philip Shilane,2008-10-01 In recent years there has been enormous growth in the number of 3D models and their availability to a wide segment of the population Examples include the National Design Repository which stores 3D computer aided design CAD models the Protein Data Bank PDB that has atomic positions for protein molecules and the Princeton Shape Benchmark with thousands of everyday objects represented as

polygonal surface models With the availability of free interactive tools for creating 3D models and graphics cards for home computers we can expect 3D data to become ever more widely available The first contribution of this research is an analysis technique to select the most important or distinctive regions of an object Our approach identifies regions of a surface that have shape consistent with objects of the same type and different from objects of other types The second contribution is a new methodology to analyze shape retrieval methods with a common data set of classified 3D models and software tools called the Princeton Shape Benchmark This text should be especially useful to researchers in computer graphics computer vision CAD and information retrieval

View-based Models of 3D Object Recognition and Class-specific Invariances

Massachusetts Institute of Technology. Artificial Intelligence Laboratory, Nikos K. Logothetis, Thomas Vetter, Anya Hurlbert, Tomaso Poggio, 1994

Representations and Techniques for 3D Object Recognition and Scene Interpretation

Derek Hoiem, Silvio Savarese, 2011 One of the grand challenges of artificial intelligence is to enable computers to interpret

3D scenes and objects from imagery This book organizes and introduces major concepts in 3D scene and object representation and inference from still images with a focus on recent efforts to fuse models of geometry and perspective with statistical machine learning The book is organized into three sections 1 Interpretation of Physical Space 2 Recognition of 3D Objects and 3 Integrated 3D Scene Interpretation The first discusses representations of spatial layout and techniques to interpret physical scenes from images The second section introduces representations for 3D object categories that account for the intrinsically 3D nature of objects and provide robustness to change in viewpoints The third section discusses strategies to unite inference of scene geometry and object pose and identity into a coherent scene interpretation Each section broadly surveys important ideas from cognitive science and artificial intelligence research organizes and discusses key concepts and techniques from recent work in computer vision and describes a few sample approaches in detail Newcomers to computer vision will benefit from introductions to basic concepts such as single view geometry and image classification while experts and novices alike may find inspiration from the book's organization and discussion of the most recent ideas in 3D scene understanding and 3D object recognition Specific topics include mathematics of perspective geometry visual elements of the physical scene structural 3D scene representations techniques and features for image and region categorization historical perspective computational models and datasets and machine learning techniques for 3D object recognition inferences of geometrical attributes of objects such as size and pose and probabilistic and feature passing approaches for contextual reasoning about 3D objects and scenes Table of Contents Background on 3D Scene Models Single view Geometry Modeling the Physical Scene Categorizing Images and Regions Examples of 3D Scene Interpretation Background on 3D Recognition Modeling 3D Objects Recognizing and Understanding 3D Objects Examples of 2D 1 2 Layout Models Reasoning about Objects and Scenes Cascades of Classifiers Conclusion and Future Directions

3D Object Retrieval 2011, 2011

View-Based Strategies for 3D Object Recognition, 1994 A persistent issue of debate in the area of

3D object recognition concerns the nature of the experimentally acquired object models in the primate visual system. One prominent proposal in this regard has expounded the use of object centered models such as representations of the objects 3D structures in a coordinate frame independent of the viewing parameters (Marr and Nishihara 1978). In contrast to this is another proposal which suggests that the viewing parameters encountered during the learning phase might be inextricably linked to subsequent performance on a recognition task (Tarr and Pinker 1989; Poggio and Edelman 1990). The object model according to this idea is simply a collection of the sample views encountered during training. Given that object centered recognition strategies have the attractive feature of leading to viewpoint independence they have garnered much of the research effort in the field of computational vision. Furthermore since human recognition performance seems remarkably robust in the face of imaging variations (Ellis et al 1989) it has often been implicitly assumed that the visual system employs an object centered strategy. In the present study we examine this assumption more closely. Our experimental results with a class of novel 3D structures strongly suggest the use of a view based strategy by the human visual system even when it has the opportunity of constructing and using object centered models. In fact for our chosen class of objects the results seem to support a stronger claim: 3D object recognition is 2D view based.

Graph-Based Combinations of Fragment

Descriptors for Improved 3D Object Retrieval Tobias Schreck, Maximilian Scherer, Michael Walter, Benjamin Bustos, Sang Min Yoon, Arjan Kuijper, 2013 [Appearance-based 3-D Object Recognition and Pose Estimation](#) Chiranjeev Lal

Chowdhary, 2011-01 In Computer Vision Image Processing Artificial Intelligence and Neural Networks object recognition is one of the most successful applications of image or object analysis and understanding. The recognition system typically involves some sort of sensor, the use of a model database in which all the objects models representations are saved and a decision making ability. When a sensor views an object the digitized image is processed so as to represent it in the same way as the models are represented in the databases. Then a recognition algorithm tries to find the model to which the object best matches. For the view based recognition the representations take into account the appearance of the object. To achieve 3D Object recognition 3DOR the pose of objects are also saved in the database. In general two 3DOR techniques. They are Geometric feature based approach and Appearance based approach. The geometric feature based approach uses properties of shape of object i.e. lines, curves and vertices for object recognition descriptions. But appearance based 3DOR is the combined effects of objects shape, reflectance properties, pose and the illumination.

3DOR , Workshop on 3D Object Retrieval (3DOR) , 2014 *User-drawn Sketch-based 3D Object Retrieval Using Sparse Coding* Sang Min Yoon, Gang-Joon

Yoon, Tobias Schreck, 2015 **Features for 3D Object Retrieval** Cristina González Delgado, 2016 This project is focused on the object retrieval challenging field, a critical area for robotics and computer vision systems. Specifically this project is trying to address some issues in the object recognition area which is a key during the object retrieval process. Recently low cost RGB-D sensors able to capture not only color information but also depth data have emerged. This is a great opportunity to

increment efficiency and robustness of object retrieval applications by taking advantage of this additional depth information. In this project I implemented an evaluation system of 3D feature descriptors by using the Point Cloud Library PCL and used it to perform an specific assessment for two of the most widely used descriptors for object recognition SHOTColor and PFHColor. They were tested in two different datasets containing data extracted with the Kinect RGB D sensor. The first dataset consist of 3D point clouds of individual objects and synthetically built scenes the second one has 3D point clouds corresponding to individual model objects and scenes from the real world. The evaluation process was done considering the following three properties: descriptiveness, robustness to Gaussian noise impact and support radius variation and efficiency. As a final result the outcome of this evaluation process is the performance assessment on those descriptors depending on the different scenarios. SHOTColor descriptors performed better in terms of descriptiveness, robustness to Gaussian noise impact and support radius variations and efficiency as well. But they required higher storage capacity than PFHColor descriptors. SHOTColor descriptors seems to be more sensitive to clutter and occlusion effects since the performance for the real scenes dataset is worsening faster than the PFHColor one. Given those considerations SHOTColor descriptors are recommended as the best option for time crucial applications and also for those ones requiring a strong descriptiveness power. On the other hand PFHColor descriptors are better for spacial crucial applications.

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