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web now since you know that the system is in equilibrium this means that force of tension must exert a torque equal in magnitude to the total torque due to gravity you can create

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web the first condition necessary to achieve equilibrium is the one already mentioned the net external force on the system must be zero expressed as an equation this is simply $\sum \vec{F} = 0$

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web in physics equilibrium is the state in which all the individual forces and torques exerted upon an object are balanced this principle is applied to the analysis of objects in static

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web $\sum \vec{F} = 0$ will not give any equation thus using static equilibrium condition we cannot find the forces let us consider the axial deformations of rods for rod 1 $\delta l = \frac{F l}{A E}$

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web overview newton's laws of motion first law inertia second law $\vec{F}_{net} = m\vec{a}$ third law action reaction pairs gravity $m_1\vec{g}$ $m_2\vec{g}$ $m_3\vec{g}$ $m_4\vec{g}$ $m_5\vec{g}$ $m_6\vec{g}$ $m_7\vec{g}$ $m_8\vec{g}$ $m_9\vec{g}$ $m_{10}\vec{g}$ $m_{11}\vec{g}$ $m_{12}\vec{g}$ $m_{13}\vec{g}$ $m_{14}\vec{g}$ $m_{15}\vec{g}$ $m_{16}\vec{g}$ $m_{17}\vec{g}$ $m_{18}\vec{g}$ $m_{19}\vec{g}$ $m_{20}\vec{g}$ $m_{21}\vec{g}$ $m_{22}\vec{g}$ $m_{23}\vec{g}$ $m_{24}\vec{g}$ $m_{25}\vec{g}$ $m_{26}\vec{g}$ $m_{27}\vec{g}$ $m_{28}\vec{g}$ $m_{29}\vec{g}$ $m_{30}\vec{g}$ $m_{31}\vec{g}$ $m_{32}\vec{g}$ $m_{33}\vec{g}$ $m_{34}\vec{g}$ $m_{35}\vec{g}$ $m_{36}\vec{g}$ $m_{37}\vec{g}$ $m_{38}\vec{g}$ $m_{39}\vec{g}$ $m_{40}\vec{g}$ $m_{41}\vec{g}$ $m_{42}\vec{g}$ $m_{43}\vec{g}$ $m_{44}\vec{g}$ $m_{45}\vec{g}$ $m_{46}\vec{g}$ $m_{47}\vec{g}$ $m_{48}\vec{g}$ $m_{49}\vec{g}$ $m_{50}\vec{g}$ $m_{51}\vec{g}$ $m_{52}\vec{g}$ $m_{53}\vec{g}$ $m_{54}\vec{g}$ $m_{55}\vec{g}$ 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